

GAME AI

with Jeff Wilson, PhD

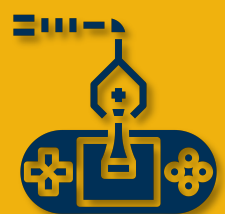
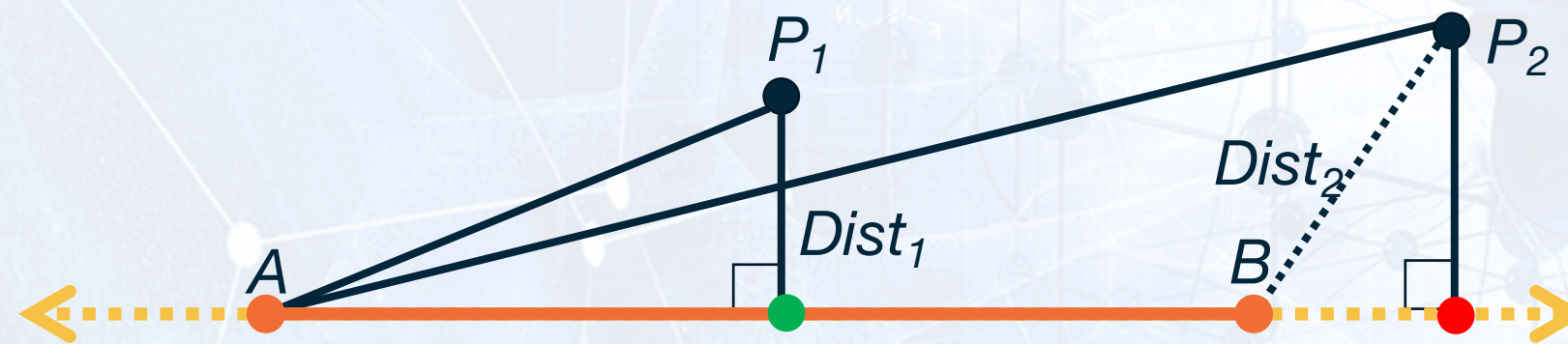
Computational Geometry for Game AI

Distance of Point to Line Segment



Distance of Point to Line Segment

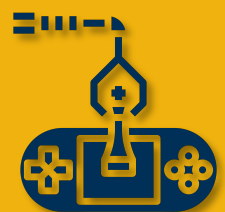
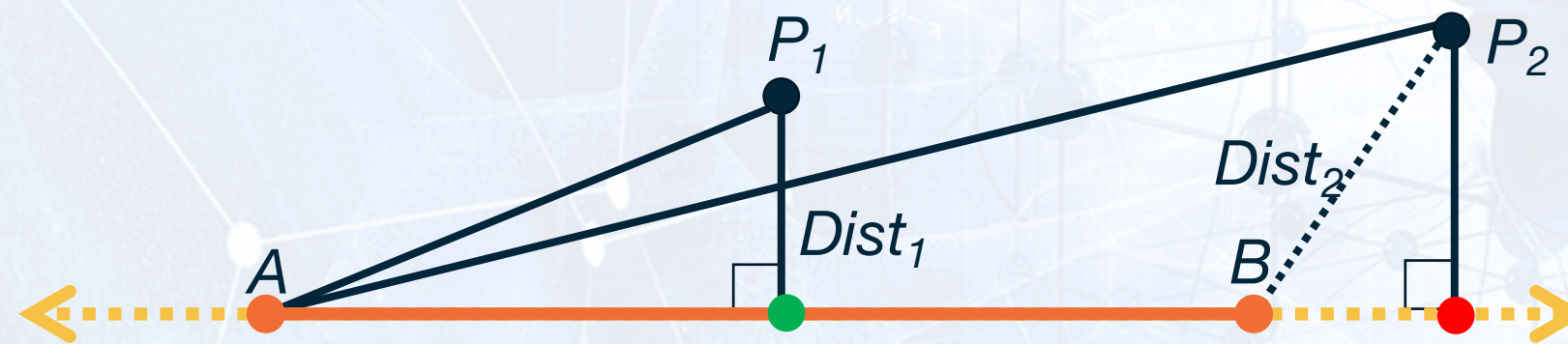
- ◆ Floating point for calculation
 - ◆ Can cast mapped integers to floats or use original floats
 - ◆ Computational Geometry FP concerns are diminished but keep in mind for extreme cases with large exponents which could be encountered (consider PCG)



**Point to Line Segment
Distance**

Distance of Point to Line Segment

- Algorithm has multiple steps
 - Find closest point (cp) to P on the infinite line that is coincident with the line segment AB (via projection with AP or BP)
 - Test whether cp is between A and B via vector line equation, checking scalar t in range $[0, 1]$. Is between?
 - YES – return distance between P and cp
 - NO – select from A and B which is closer to cp , then return distance from P to closer of the two



**Point to Line Segment
Distance**

Distance of Point to Line Segment

- ◆ Nice optimization to avoid Square Root

$$\mathbf{a}_1 = a_1 \hat{\mathbf{b}}$$

$$a_1 = \|\mathbf{a}\| \cos \theta = \mathbf{a} \cdot \hat{\mathbf{b}} = \mathbf{a} \cdot \frac{\mathbf{b}}{\|\mathbf{b}\|}$$

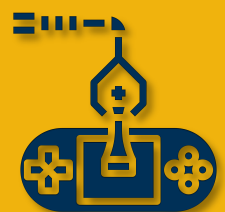
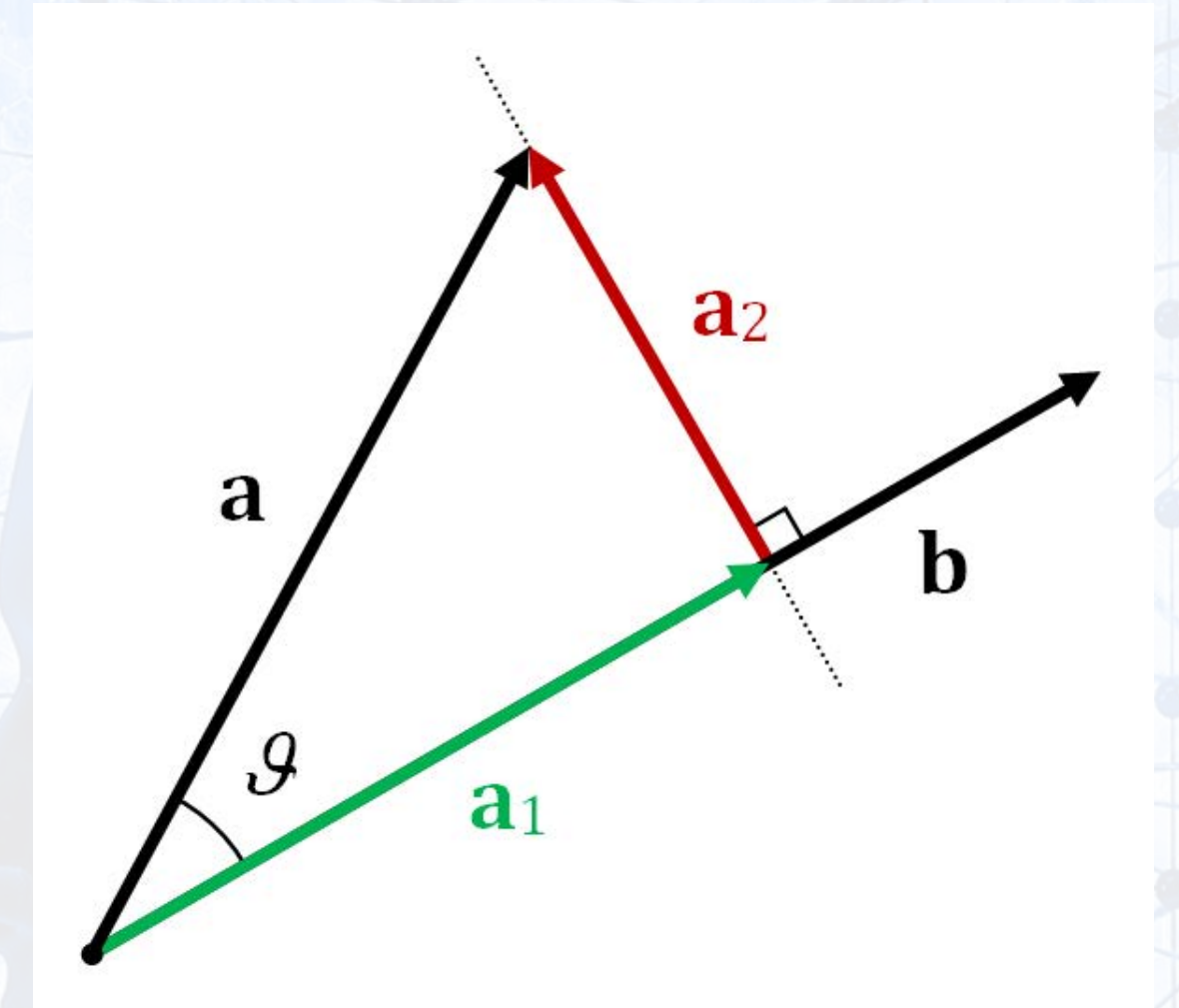
$$\mathbf{a}_1 = \left(\mathbf{a} \cdot \frac{\mathbf{b}}{\|\mathbf{b}\|} \right) \frac{\mathbf{b}}{\|\mathbf{b}\|}$$

$$\mathbf{a}_1 = \frac{(\mathbf{a} \cdot \mathbf{b}) \mathbf{b}}{\|\mathbf{b}\|^2} \leftarrow \text{Got rid of the Square Root!}$$

And we have a normalized scalar that will be in range [0, 1] if on the line!

$$t = \frac{(\mathbf{a} \cdot \mathbf{b})}{\|\mathbf{b}\|^2}$$

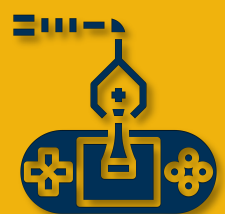
$$\mathbf{a}_1 = t \mathbf{b}$$



Point to Line Segment Distance

Error Checking

- Need to check if line segment points A and B are the same
- If so, return the distance from test point to either A or B
- Must do this to avoid divide by zero



**Point to Line Segment
Distance**